$$
\text { Let } \theta=\lambda t \sin 3 t
$$

$$
\frac{d \theta}{d t}=\alpha \sin 3 t+\beta t \cos 3 t \text { and }
$$

$$
\frac{d^{2} \theta}{d t^{2}}=\delta \cos 3 t+\gamma t \sin 3 t
$$

$\frac{d \theta}{d t}=\lambda \sin 3 t+3 \lambda t \cos 3 t$ and

$$
\begin{aligned}
\frac{d^{2} \theta}{d t^{2}} & =3 \lambda \cos 3 t+3 \lambda \cos 3 t \\
& -9 \lambda t \sin 3 t \\
& =6 \lambda \cos 3 t-9 \lambda t \sin 3 t
\end{aligned}
$$

$6 \lambda \cos 3 t-9 \lambda t \sin 3 t$ $+9(\lambda t \sin 3 t)$ $=\frac{1}{2} \cos 3 t \Rightarrow \lambda=\ldots$
$\theta=\frac{1}{12} t \sin 3 t *$
(a)(ii)
(b)
(c)
0.662 is close to 0.62 so a good model (at $t=10$ )
(d)
$\frac{d^{2} \theta}{d t^{2}}+9 \theta=0$ oe

A1*
2.1

B1ft
1.1b
$\begin{array}{ll}\text { dM1 } & 3.4\end{array}$
M1 1.1b

A1 1.1b
dM1 1.1b
A1 1.1b
(4)

| M1 | 3.4 |
| :--- | :--- |


| M1 | 3.4 |
| :--- | :--- |

ddM1 1.1b
A1 3.4
(4)

31ft 3.5a

B1 3.5 c

## Notes:

## (a)(i) Note: mark (a) as a whole

M1: Differentiates the given PI twice using the product rule to achieve the required form.
Alternatively, uses a correct form for the PI and differentiates twice using the product rule to achieve the required form. A correct form may involve other terms with coefficients that will be zero, e.g.
$\theta=\lambda t \sin 3 t+\mu t \cos 3 t$ is fine. Also allow e.g $\theta=\lambda t \sin \quad \omega t$
A1: Correct derivatives.
dM1: Depends on first M, substitutes into the given differential equation and attempts to simplify. In the Alt they must go on to find value for $\lambda$.
A1*: Achieves $\frac{1}{2} \cos 3$ tand makes a minimal conclusion (e.g //). Alternatively reaches the correct PI.
(a)(ii)

M1: Uses the model to form and solve the auxiliary equation. Accept $m^{2}+9=0 \rightarrow m= \pm 3 i$ or $\pm$ 3
A1: Correct complementary function. Must be in terms of $t$ but allow recovery if initially in terms of $x$ but changed later.
dM1: Dependent on the previous method mark. Finds the general solution by adding the particular integral to the complementary function.
A1: Correct general solution including " $\theta=$ ", which may be recovered in part (b).
(b)

M1: Uses the initial conditions of the model, $t=0, \theta=\frac{\pi}{3}$ to find a value for a constant.
M1: Differentiates the general solution and uses the initial conditions of the model $t=0, \frac{d \theta}{d t}=0$ to find a value for the other constant.
ddM1: Dependent on both previous method marks. Substitutes $t=10$ into their particular solution. If not substitution is seen, accept any value as the attempt as long as they have found all relevant constants.
A1: Accept awrt $\pm 0.662$
(c)

B1ft: Makes a quantitative comparison of the size of their answer to part (b) with 0.62 and makes conclusion (e.g. good model). Follow through on their answer to (b) and draws an appropriate conclusion about the model. Accept "not reasonable" as long as it is supported with evidence but there must be some instructive comparison and a conclusion about the model - not just stating how much it is out. The reason given must be correct.
Accept e.g. a correct percentage error with reasonable conclusion, or statement approximately equal with conclusion.
Do not accept e.g. "does not agree to 1 s.f." or "out by 0.6 " as these lacks context. Do not accept arguments based solely on a difference in sign, they must be referring to the relative size of angle.
(d)

B1: Refines the model, accept any constant on the right hand side.

